

Asymptotic Estimates in Information Theory with Non-Vanishing Error Probabilities

Vincent Y. F. Tan

Dept. of ECE and Dept. of Mathematics
National University of Singapore (NUS)

September 2014

Acknowledgements

This is joint work with

1 Sy-Quoc Le and Mehul Motani (NUS)



2 Jon Scarlett (Cambridge, now at EPFL)



1 Motivation, Background and History

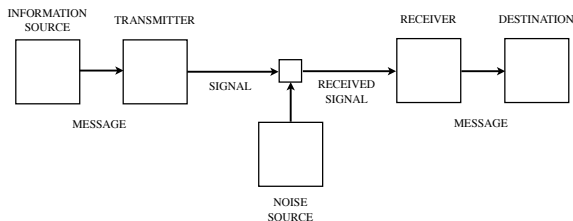
- 1 Motivation, Background and History
- 2 Gaussian Interference Channel with Very Strong Interference

- 1 Motivation, Background and History
- 2 Gaussian Interference Channel with Very Strong Interference
- 3 Gaussian MAC with Degraded Message Sets

- 1 Motivation, Background and History
- 2 Gaussian Interference Channel with Very Strong Interference
- 3 Gaussian MAC with Degraded Message Sets
- 4 Conclusion

- 1 Motivation, Background and History
- 2 Gaussian Interference Channel with Very Strong Interference
- 3 Gaussian MAC with Degraded Message Sets
- 4 Conclusion

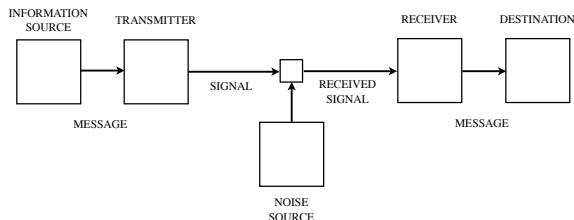
Transmission of Information



Shannon's Figure 1

- Information theory \equiv Finding fundamental limits for **reliable** information transmission

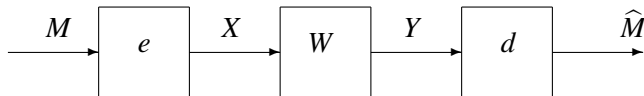
Transmission of Information



Shannon's Figure 1

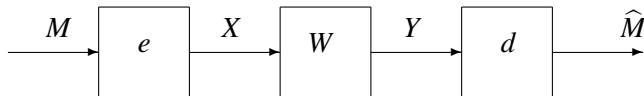
- Information theory \equiv Finding fundamental limits for **reliable** information transmission
- **Channel coding**: Concerned with the maximum rate of communication in bits/channel use

Channel Coding (One-Shot)



- A **code** is an triple $\mathcal{C} = \{\mathcal{M}, e, d\}$ where \mathcal{M} is the message set and $b(e(m)) \leq S$ for some cost function $b(\cdot)$ and cost S

Channel Coding (One-Shot)

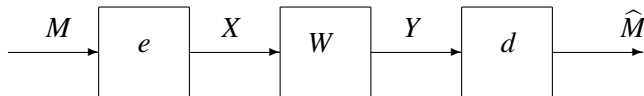


- A **code** is a triple $\mathcal{C} = \{\mathcal{M}, e, d\}$ where \mathcal{M} is the message set and $b(e(m)) \leq S$ for some cost function $b(\cdot)$ and cost S
- The **average error probability** $p_{\text{err}}(\mathcal{C})$ is

$$p_{\text{err}}(\mathcal{C}) := \Pr[\hat{M} \neq M]$$

where M is uniform on \mathcal{M}

Channel Coding (One-Shot)



- A **code** is an triple $\mathcal{C} = \{\mathcal{M}, e, d\}$ where \mathcal{M} is the message set and $b(e(m)) \leq S$ for some cost function $b(\cdot)$ and cost S
- The **average error probability** $p_{\text{err}}(\mathcal{C})$ is

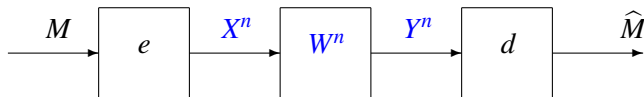
$$p_{\text{err}}(\mathcal{C}) := \Pr \left[\hat{M} \neq M \right]$$

where M is uniform on \mathcal{M}

- A **non-asymptotic fundamental limit** can be defined as

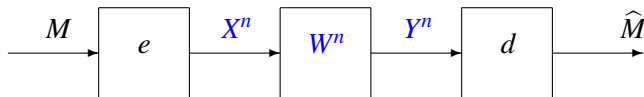
$$M^*(W, \varepsilon, S) := \sup \left\{ m \in \mathbb{N} \mid \exists \mathcal{C} \text{ s.t. } m = |\mathcal{M}|, p_{\text{err}}(\mathcal{C}) \leq \varepsilon \right\}$$

Channel Coding (n -Shot) for AWGN



- Consider n independent uses of an **additive white Gaussian channel** W^n

Channel Coding (n -Shot) for AWGN



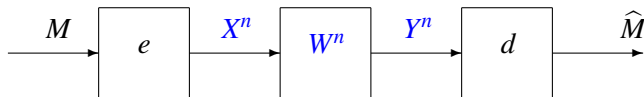
- Consider n independent uses of an **additive white Gaussian channel** W^n
- For vectors $\mathbf{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$ and $\mathbf{y} := (y_1, \dots, y_n) \in \mathbb{R}^n$, with

$$\|\mathbf{x}\|_2^2 \leq nS,$$

the channel law is

$$W^n(\mathbf{y}|\mathbf{x}) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(y_i - x_i)^2}{2}\right)$$

Channel Coding (n -Shot) for AWGN



- Consider n independent uses of an **additive white Gaussian channel** W^n
- For vectors $\mathbf{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$ and $\mathbf{y} := (y_1, \dots, y_n) \in \mathbb{R}^n$, with

$$\|\mathbf{x}\|_2^2 \leq nS,$$

the channel law is

$$W^n(\mathbf{y}|\mathbf{x}) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(y_i - x_i)^2}{2}\right)$$

- **Non-asymptotic fundamental limit** for n uses of W

$$M^*(W^n, \varepsilon, S)$$

Single-User Asymptotic Evaluation

Theorem (Hayashi (2009), Polyanskiy-Poor-Verdú (2010), Tan-Tomamichel (2014))

For every $\varepsilon \in (0, 1)$, we have

$$\log M^*(W^n, \varepsilon, S) = nC(S) + \sqrt{nV(S)}\Phi^{-1}(\varepsilon) + \frac{1}{2}\log n + O(1)$$

*where $C(S)$ and $V(S)$ are the **capacity** and **dispersion** defined as*

$$C(S) = \frac{1}{2}\log(1 + S), \quad V(S) = \frac{S(S + 2)}{(S + 1)^2} \log^2 e$$

Single-User Asymptotic Evaluation

Theorem (Hayashi (2009), Polyanskiy-Poor-Verdú (2010), Tan-Tomamichel (2014))

For every $\varepsilon \in (0, 1)$, we have

$$\log M^*(W^n, \varepsilon, S) = nC(S) + \sqrt{nV(S)}\Phi^{-1}(\varepsilon) + \frac{1}{2}\log n + O(1)$$

where $C(S)$ and $V(S)$ are the *capacity* and *dispersion* defined as

$$C(S) = \frac{1}{2} \log(1 + S), \quad V(S) = \frac{S(S + 2)}{(S + 1)^2} \log^2 e$$



M. Hayashi



Polyanskiy-Poor-Verdú



M. Tomamichel



Single-User Asymptotic Evaluation: Interpretation

$$R^*(W^n, \varepsilon, S) := \frac{\log M^*(W^n, \varepsilon, S)}{n} = \underbrace{C(S) + \sqrt{\frac{V(S)}{n}} \Phi^{-1}(\varepsilon)}_{\text{Gaussian approximation}} + O\left(\frac{\log n}{n}\right)$$

Single-User Asymptotic Evaluation: Interpretation

$$R^*(W^n, \varepsilon, S) := \frac{\log M^*(W^n, \varepsilon, S)}{n} = \underbrace{C(S) + \sqrt{\frac{V(S)}{n}} \Phi^{-1}(\varepsilon)}_{\text{Gaussian approximation}} + O\left(\frac{\log n}{n}\right)$$

- Interpretation: The backoff from $C(S)$ at finite blocklength n and tolerable error probability is approximately

$$\sqrt{\frac{V(S)}{n}} \Phi^{-1}(1 - \varepsilon)$$

- Small ε implies large backoff

Single-User Asymptotic Evaluation: Interpretation

$$R^*(W^n, \varepsilon, S) := \frac{\log M^*(W^n, \varepsilon, S)}{n} = \underbrace{C(S) + \sqrt{\frac{V(S)}{n}} \Phi^{-1}(\varepsilon)}_{\text{Gaussian approximation}} + O\left(\frac{\log n}{n}\right)$$

- Interpretation: The backoff from $C(S)$ at finite blocklength n and tolerable error probability is approximately

$$\sqrt{\frac{V(S)}{n}} \Phi^{-1}(1 - \varepsilon)$$

- Small ε implies large backoff
- Can compare to actual finite blocklength bounds
- Gaussian approximation is good for some n and ε

Background: Shannon's Channel Coding Theorem

- Shannon's **noisy channel coding theorem** and
- Shannon's (1959), Yoshihara's (1964) and Wolfowitz's (1978) **strong converse** state that



Background: Shannon's Channel Coding Theorem

- Shannon's **noisy channel coding theorem** and
- Shannon's (1959), Yoshihara's (1964) and Wolfowitz's (1978) **strong converse** state that



Theorem (Shannon (1949), Shannon (1959))

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log M^*(W^n, \varepsilon, S) = C(S), \quad \forall \varepsilon \in (0, 1)$$

Background: Shannon's Channel Coding Theorem

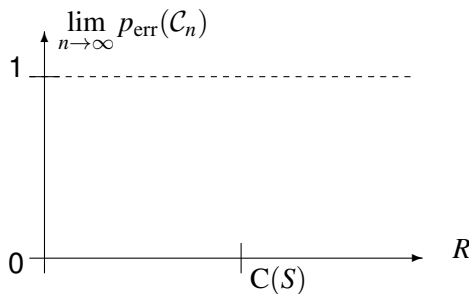
$$\lim_{n \rightarrow \infty} \frac{1}{n} \log M^*(W^n, \varepsilon, S) = C(S) \quad \text{bits/channel use}$$

- Channel coding theorem for AWGN channels is independent of $\varepsilon \in (0, 1)$

Background: Shannon's Channel Coding Theorem

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log M^*(W^n, \varepsilon, S) = C(S) \quad \text{bits/channel use}$$

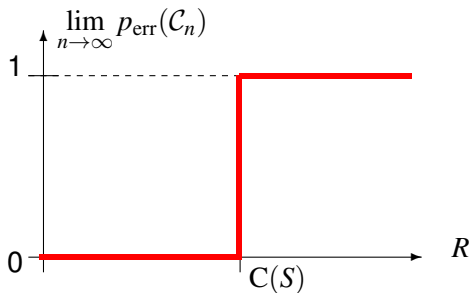
- Channel coding theorem for AWGN channels is independent of $\varepsilon \in (0, 1)$



Background: Shannon's Channel Coding Theorem

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log M^*(W^n, \varepsilon, S) = C(S) \quad \text{bits/channel use}$$

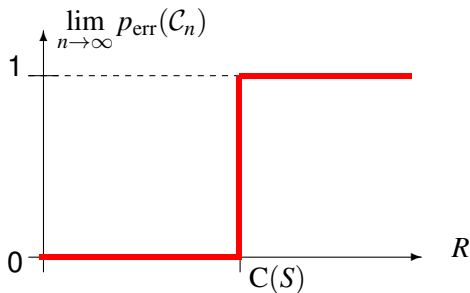
- Channel coding theorem for AWGN channels is independent of $\varepsilon \in (0, 1)$



Background: Shannon's Channel Coding Theorem

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log M^*(W^n, \varepsilon, S) = C(S) \quad \text{bits/channel use}$$

- Channel coding theorem for AWGN channels is independent of $\varepsilon \in (0, 1)$



- Phase transition at capacity

Background: Second-Order Coding Rates

- What happens **at capacity**?

Background: Second-Order Coding Rates

- What happens **at capacity**?
- More precisely, what happens when

$$\log |\mathcal{M}_n| \approx nC(S) + L\sqrt{n}$$

for some $L \in \mathbb{R}$?

Background: Second-Order Coding Rates

- What happens **at capacity**?
- More precisely, what happens when

$$\log |\mathcal{M}_n| \approx nC(S) + L\sqrt{n}$$

for some $L \in \mathbb{R}$?

- Here L is known as the **second-order coding rate** of the code

Background: Second-Order Coding Rates

- What happens **at capacity**?
- More precisely, what happens when

$$\log |\mathcal{M}_n| \approx nC(S) + L\sqrt{n}$$

for some $L \in \mathbb{R}$?

- Here L is known as the **second-order coding rate** of the code
- Note that L can be negative (cf. Hayashi (2008), Hayashi (2009))

Background: Second-Order Coding Rates

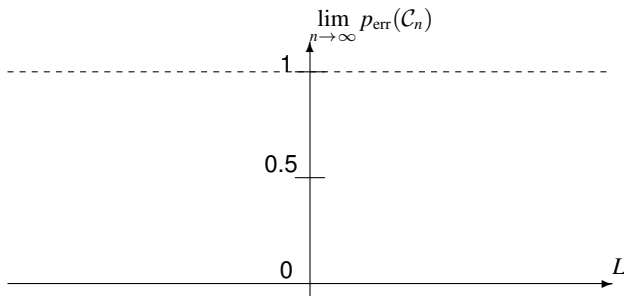
Assume rate of the code satisfies

$$\frac{1}{n} \log |\mathcal{M}_n| = C(S) + \frac{L}{\sqrt{n}} + o\left(\frac{1}{\sqrt{n}}\right)$$

Background: Second-Order Coding Rates

Assume rate of the code satisfies

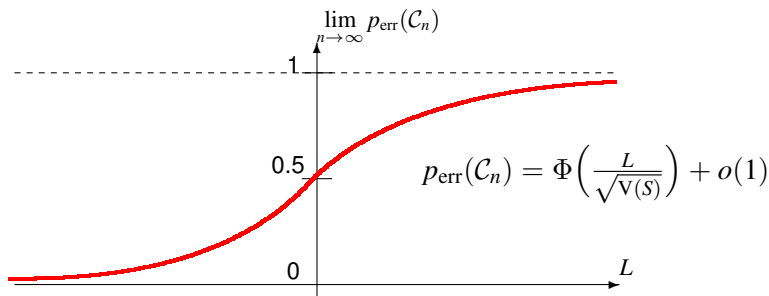
$$\frac{1}{n} \log |\mathcal{M}_n| = C(S) + \frac{L}{\sqrt{n}} + o\left(\frac{1}{\sqrt{n}}\right)$$



Background: Second-Order Coding Rates

Assume rate of the code satisfies

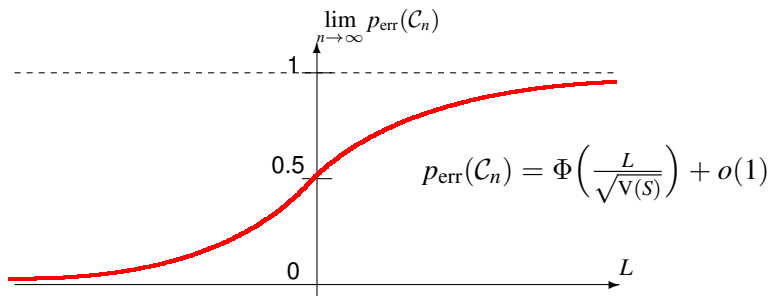
$$\frac{1}{n} \log |\mathcal{M}_n| = C(S) + \frac{L}{\sqrt{n}} + o\left(\frac{1}{\sqrt{n}}\right)$$



Background: Second-Order Coding Rates

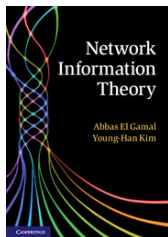
Assume rate of the code satisfies

$$\frac{1}{n} \log |\mathcal{M}_n| = C(S) + \frac{L}{\sqrt{n}} + o\left(\frac{1}{\sqrt{n}}\right)$$



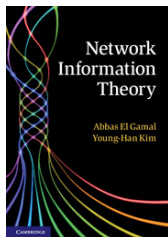
For an error probability ε , the **optimum second-order coding rate** is

$$L^*(\varepsilon) := \sqrt{V(S)} \Phi^{-1}(\varepsilon)$$



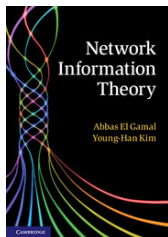
Network Information Theory
by A. El Gamal and Y.-H. Kim

- Many problems unsolved



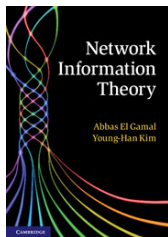
Network Information Theory
by A. El Gamal and Y.-H. Kim

- Many problems unsolved
- My agenda is to understand second-order behavior of solved NIT problems



Network Information Theory
by A. El Gamal and Y.-H. Kim

- Many problems unsolved
- My agenda is to understand second-order behavior of solved NIT problems
- Gain new insights on second-order optimal coding schemes

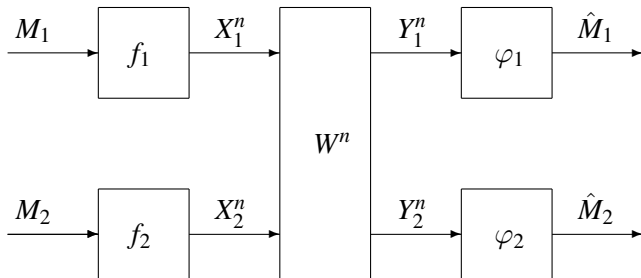


Network Information Theory
by A. El Gamal and Y.-H. Kim

- Many problems unsolved
- My agenda is to understand second-order behavior of solved NIT problems
- Gain new insights on second-order optimal coding schemes
- We study two simple NIT problems in the rest of the talk

- 1 Motivation, Background and History
- 2 Gaussian Interference Channel with Very Strong Interference
- 3 Gaussian MAC with Degraded Message Sets
- 4 Conclusion

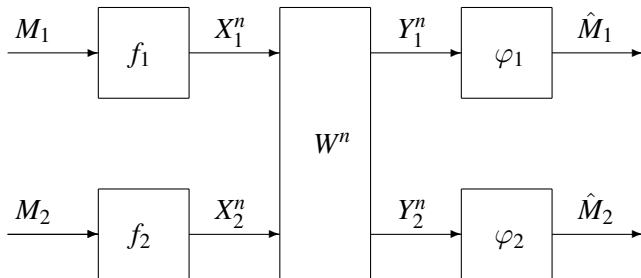
Gaussian Interference Channel



- Two-sender two-receiver GIC is given as

$$Y_{1i} = g_{11}X_{1i} + g_{12}X_{2i} + Z_{1i}, \quad Y_{2i} = g_{21}X_{1i} + g_{22}X_{2i} + Z_{2i}$$

Gaussian Interference Channel



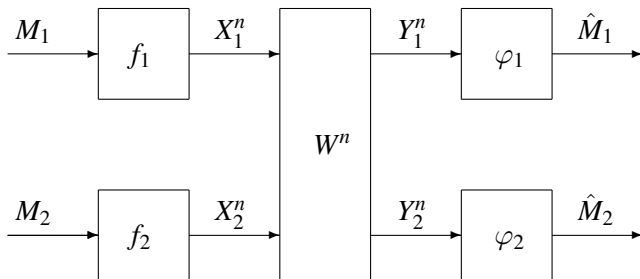
- Two-sender two-receiver GIC is given as

$$Y_{1i} = g_{11}X_{1i} + g_{12}X_{2i} + Z_{1i}, \quad Y_{2i} = g_{21}X_{1i} + g_{22}X_{2i} + Z_{2i}$$

- Channel inputs are power limited

$$\sum_{i=1}^n X_{ji}^2 \leq nS_j, \quad j = 1, 2$$

Gaussian Interference Channel



- Two-sender two-receiver GIC is given as

$$Y_{1i} = g_{11}X_{1i} + g_{12}X_{2i} + Z_{1i}, \quad Y_{2i} = g_{21}X_{1i} + g_{22}X_{2i} + Z_{2i}$$

- Channel inputs are power limited

$$\sum_{i=1}^n X_{ji}^2 \leq nS_j, \quad j = 1, 2$$

- Capacity region is an **open problem** in NIT

Very Strong Inference

- Define the **signal-to-noise ratios** as

$$\text{snr}_1 = g_{11}^2 S_1, \quad \text{snr}_2 = g_{22}^2 S_2$$

- Define the **interference-to-noise ratios** as

$$\text{inr}_1 = g_{12}^2 S_2, \quad \text{inr}_2 = g_{21}^2 S_1$$

Very Strong Inference

- Define the **signal-to-noise ratios** as

$$\text{snr}_1 = g_{11}^2 S_1, \quad \text{snr}_2 = g_{22}^2 S_2$$

- Define the **interference-to-noise ratios** as

$$\text{inr}_1 = g_{12}^2 S_2, \quad \text{inr}_2 = g_{21}^2 S_1$$

- A GIC is said to have **strictly very strong interference (SVSI)** if

$$\text{snr}_1 < \frac{\text{inr}_2}{1 + \text{snr}_2}, \quad \text{snr}_2 < \frac{\text{inr}_1}{1 + \text{snr}_1}$$

- Equivalently

$$C(\text{snr}_1) + C(\text{snr}_2) < \min\{C(\text{snr}_1 + \text{inr}_1), C(\text{snr}_2 + \text{inr}_2)\}$$

Very Strong Inference

- Define the **signal-to-noise ratios** as

$$\text{snr}_1 = g_{11}^2 S_1, \quad \text{snr}_2 = g_{22}^2 S_2$$

- Define the **interference-to-noise ratios** as

$$\text{inr}_1 = g_{12}^2 S_2, \quad \text{inr}_2 = g_{21}^2 S_1$$

- A GIC is said to have **strictly very strong interference (SVSI)** if

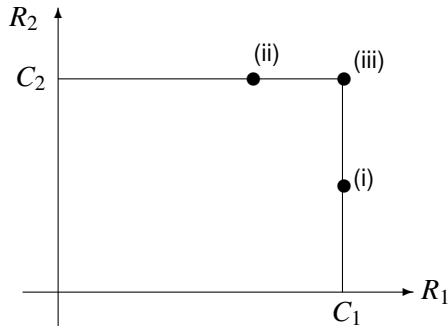
$$\text{snr}_1 < \frac{\text{inr}_2}{1 + \text{snr}_2}, \quad \text{snr}_2 < \frac{\text{inr}_1}{1 + \text{snr}_1}$$

- Equivalently

$$C(\text{snr}_1) + C(\text{snr}_2) < \min\{C(\text{snr}_1 + \text{inr}_1), C(\text{snr}_2 + \text{inr}_2)\}$$

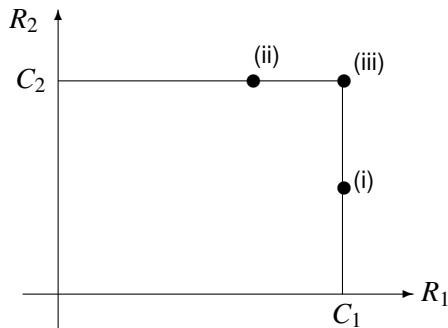
- Intuition: Receiver 1 decodes interference M_2 , then uses that to decode intended message M_1 (and vice versa)

Capacity Region for GICs with SVSI



A. Carleial

Capacity Region for GICs with SVSI

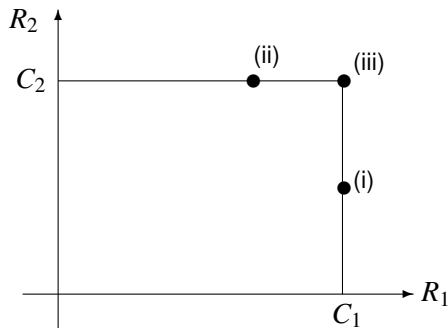


A. Carleial

- Carleial (1975) showed that the capacity region is

$$R_1 \leq C_1 := C(\text{snr}_1) \quad R_2 \leq C_2 := C(\text{snr}_2)$$

Capacity Region for GICs with SVSI



A. Carleial

- Carleial (1975) showed that the capacity region is

$$R_1 \leq C_1 := C(\text{snr}_1) \quad R_2 \leq C_2 := C(\text{snr}_2)$$

- Examine deviations of order $\frac{1}{\sqrt{n}}$ away from the boundary
- Three distinct regions.

Second-Order Coding Rate Region

- (L_1, L_2) is an (ϵ, R_1^*, R_2^*) -achievable second-order coding rate pair if there exists a sequence of $(n, M_{1n}, M_{2n}, \epsilon_n)$ -codes such that the code sizes M_{jn} satisfy

$$\liminf_{n \rightarrow \infty} \frac{1}{\sqrt{n}} (\log M_{jn} - nR_j^*) \geq L_j, \quad j = 1, 2$$

Second-Order Coding Rate Region

- (L_1, L_2) is an $(\varepsilon, R_1^*, R_2^*)$ -achievable second-order coding rate pair if there exists a sequence of $(n, M_{1n}, M_{2n}, \varepsilon_n)$ -codes such that the code sizes M_{jn} satisfy

$$\liminf_{n \rightarrow \infty} \frac{1}{\sqrt{n}} (\log M_{jn} - nR_j^*) \geq L_j, \quad j = 1, 2$$

and the average error probabilities ε_n satisfy

$$\limsup_{n \rightarrow \infty} \varepsilon_n \leq \varepsilon$$

Second-Order Coding Rate Region

- (L_1, L_2) is an $(\varepsilon, R_1^*, R_2^*)$ -achievable second-order coding rate pair if there exists a sequence of $(n, M_{1n}, M_{2n}, \varepsilon_n)$ -codes such that the code sizes M_{jn} satisfy

$$\liminf_{n \rightarrow \infty} \frac{1}{\sqrt{n}} (\log M_{jn} - nR_j^*) \geq L_j, \quad j = 1, 2$$

and the average error probabilities ε_n satisfy

$$\limsup_{n \rightarrow \infty} \varepsilon_n \leq \varepsilon$$

- If (L_1, L_2) is $(\varepsilon, R_1^*, R_2^*)$ -achievable, then there exists a sequence of codes such that

$$\log M_{jn} \geq nR_j^* + \sqrt{n}L_j + o(\sqrt{n})$$

and

$$\varepsilon_n \leq \varepsilon + o(1).$$

Optimum Second-Order Coding Rate Region

- The set of all $(\varepsilon, R_1^*, R_2^*)$ -achievable second-order coding rate pairs is called the $(\varepsilon, R_1^*, R_2^*)$ -optimum second-order coding rate region

$$\mathcal{L}(\varepsilon; R_1^*, R_2^*)$$

Optimum Second-Order Coding Rate Region

- The set of all $(\varepsilon, R_1^*, R_2^*)$ -achievable second-order coding rate pairs is called the $(\varepsilon, R_1^*, R_2^*)$ -optimum second-order coding rate region

$$\mathcal{L}(\varepsilon; R_1^*, R_2^*)$$

- Note: In the single-user case,

$$L^*(\varepsilon) := \sup \mathcal{L}(\varepsilon; R_1^* = C_1) = \sqrt{V(S_1)} \Phi^{-1}(\varepsilon)$$

- This follows from Hayashi's work (2009)

Characterize $\mathcal{L}(\varepsilon; R_1^*, R_2^*)$

- This is joint work with



S.-Q. Le (NUS)



M. Motani (NUS)

- We want to characterize $\mathcal{L}(\varepsilon; R_1^*, R_2^*)$ for all points (R_1^*, R_2^*) on the boundary of the capacity region

Characterize $\mathcal{L}(\varepsilon; R_1^*, R_2^*)$

- This is joint work with



S.-Q. Le (NUS)



M. Motani (NUS)

- We want to characterize $\mathcal{L}(\varepsilon; R_1^*, R_2^*)$ for all points (R_1^*, R_2^*) on the boundary of the capacity region
- For all (R_1^*, R_2^*) in the **interior** of the capacity region

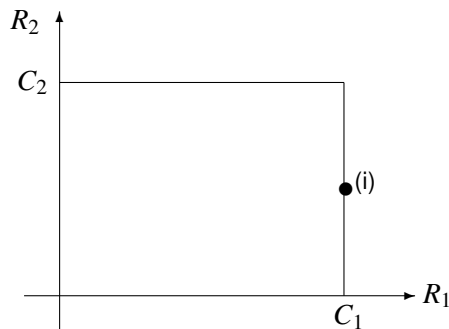
$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \mathbb{R}^2$$

- For all (R_1^*, R_2^*) in the **exterior** of the capacity region

$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \emptyset$$

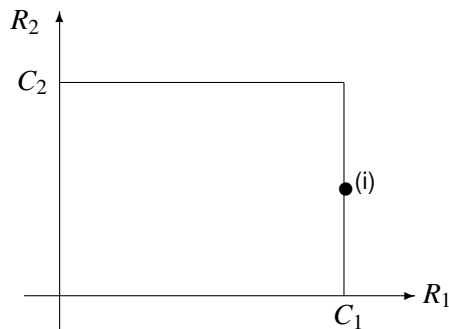
implying the **strong converse**

Main Result: Vertical Boundary



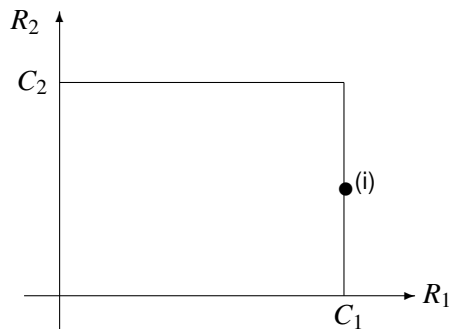
- In case (i), we are far from the horizontal boundary $R_2 < C_2$

Main Result: Vertical Boundary



- In case (i), we are far from the horizontal boundary $R_2 < C_2$
- Error event for user 2 vanishes (large deviations)

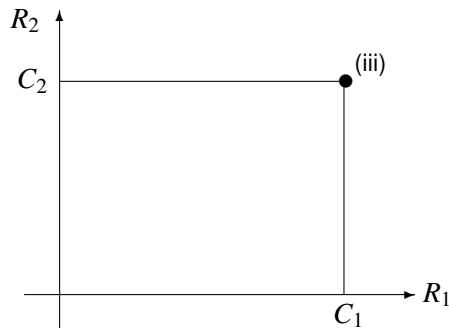
Main Result: Vertical Boundary



- In case (i), we are far from the horizontal boundary $R_2 < C_2$
- Error event for user 2 vanishes (large deviations)
- Hence second-order asymptotics only pertains to user 1

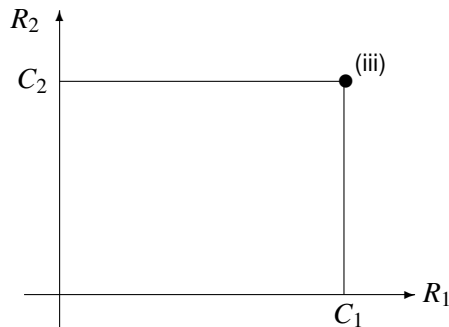
$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \{(L_1, L_2) : L_1 \leq \sqrt{V_1} \Phi^{-1}(\varepsilon)\}.$$

Main Result: Corner Point



- In case (iii), we are operating near both boundaries

Main Result: Corner Point



- In case (iii), we are operating near both boundaries
- So both constraints are active and we see L_1 and L_2 in the optimum second-order coding rate region is

$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \left\{ (L_1, L_2) : \Phi\left(-\frac{L_1}{\sqrt{V_1}}\right)\Phi\left(-\frac{L_2}{\sqrt{V_2}}\right) \geq 1 - \varepsilon \right\}.$$

Heuristic Derivation of Case (iii)

- Let $\mathcal{G}_j := \{\hat{M}_j = \hat{M}\}$ be the event that message $j = 1, 2$ is decoded correctly

$$\Pr(\mathcal{G}_1 \cap \mathcal{G}_2) \geq 1 - \varepsilon$$

Heuristic Derivation of Case (iii)

- Let $\mathcal{G}_j := \{\hat{M}_j = \hat{M}\}$ be the event that message $j = 1, 2$ is decoded correctly

$$\Pr(\mathcal{G}_1 \cap \mathcal{G}_2) \geq 1 - \varepsilon$$

- Assuming independence (which does not hold generally),

$$\Pr(\mathcal{G}_1) \Pr(\mathcal{G}_2) \geq 1 - \varepsilon$$

Heuristic Derivation of Case (iii)

- Let $\mathcal{G}_j := \{\hat{M}_j = \hat{M}\}$ be the event that message $j = 1, 2$ is decoded correctly

$$\Pr(\mathcal{G}_1 \cap \mathcal{G}_2) \geq 1 - \varepsilon$$

- Assuming independence (which does not hold generally),

$$\Pr(\mathcal{G}_1) \Pr(\mathcal{G}_2) \geq 1 - \varepsilon$$

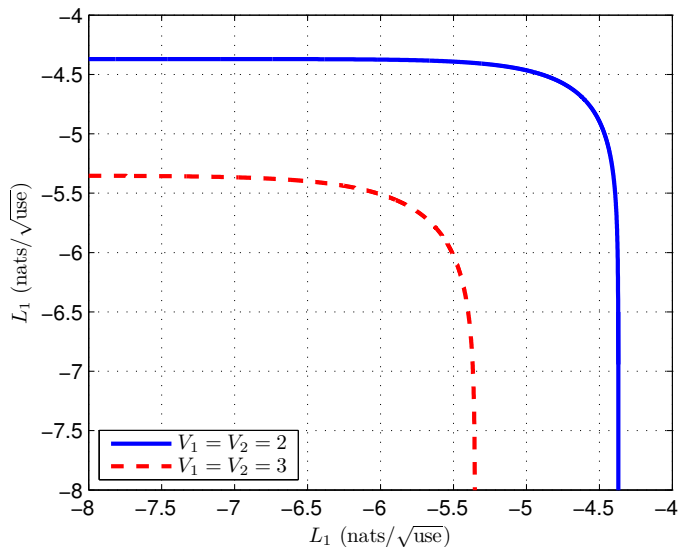
- But we know from the single-user result that the error probability

$$\Pr(\mathcal{G}_j^c) \approx \Phi\left(\frac{L_j}{\sqrt{V_j}}\right) \implies \Pr(\mathcal{G}_j) \approx \Phi\left(-\frac{L_j}{\sqrt{V_j}}\right).$$

So the set of all (ε, C_1, C_2) -achievable second-order coding rates is

$$\Phi\left(-\frac{L_1}{\sqrt{V_1}}\right)\Phi\left(-\frac{L_2}{\sqrt{V_2}}\right) \geq 1 - \varepsilon$$

Illustration of Case (iii)



- Carleial (1975) mentioned that
“Very strong interference is as innocuous as no interference at all”

Intuition Gleaned from GIC with SVSI

- Carleial (1975) mentioned that
“Very strong interference is as innocuous as no interference at all”
- We show that SVSI is innocuous in the sense that the capacities C_j and **dispersions** V_j are not affected

Intuition Gleaned from GIC with SVSI

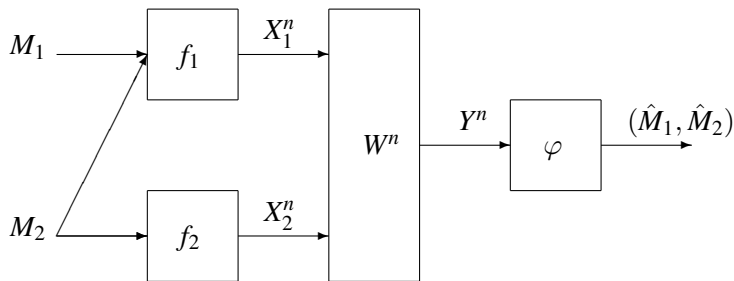
- Carleial (1975) mentioned that
“Very strong interference is as innocuous as no interference at all”
- We show that SVSI is innocuous in the sense that the capacities C_j and **dispersions** V_j are not affected
- Error events are **approximately independent**

Intuition Gleaned from GIC with SVSI

- Carleial (1975) mentioned that
“Very strong interference is as innocuous as no interference at all”
- We show that SVSI is innocuous in the sense that the capacities C_j and **dispersions** V_j are not affected
- Error events are **approximately independent**
- Intuition that the GIC with SVSI is analogous to 2 independent direct channels carries over, even in the finer second-order sense

- 1 Motivation, Background and History
- 2 Gaussian Interference Channel with Very Strong Interference
- 3 Gaussian MAC with Degraded Message Sets
- 4 Conclusion

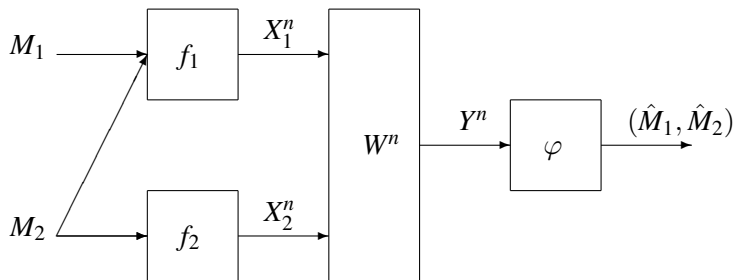
Gaussian MAC with Degraded Message Sets



- Channel law is

$$Y_i = X_{1i} + X_{2i} + Z_i$$

Gaussian MAC with Degraded Message Sets



- Channel law is

$$Y_i = X_{1i} + X_{2i} + Z_i$$

- Channel inputs are power limited

$$\sum_{i=1}^n X_{ji}^2 \leq nS_j, \quad j = 1, 2$$

Capacity Region

- Capacity region is an exercise in NIT

Capacity Region

- Capacity region is an exercise in NIT
- The capacity region is the set of all (R_1, R_2) such that

$$R_1 \leq C(S_1(1 - \rho^2))$$

$$R_1 + R_2 \leq C(S_1 + S_2 + 2\rho\sqrt{S_1S_2})$$

for some $0 \leq \rho \leq 1$.

Capacity Region

- Capacity region is an exercise in NIT
- The capacity region is the set of all (R_1, R_2) such that

$$R_1 \leq C(S_1(1 - \rho^2))$$

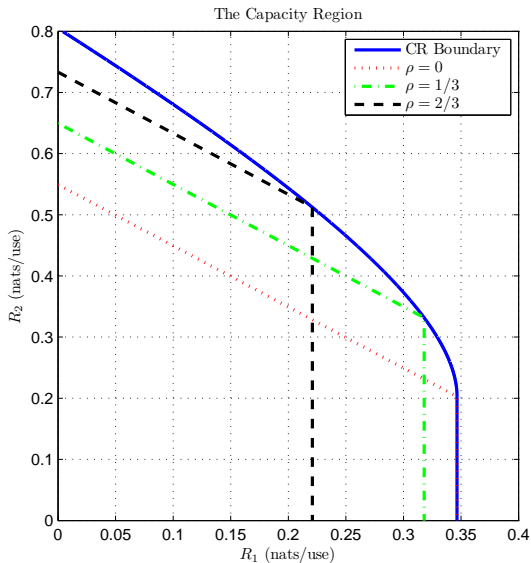
$$R_1 + R_2 \leq C(S_1 + S_2 + 2\rho\sqrt{S_1S_2})$$

for some $0 \leq \rho \leq 1$.

- Uses superposition coding (Cover (1972))



Capacity Region



Characterize $\mathcal{L}(\varepsilon; R_1^*, R_2^*)$

- This is joint work with



Jon Scarlett

- We want to characterize $\mathcal{L}(\varepsilon; R_1^*, R_2^*)$ for all points (R_1^*, R_2^*) on the boundary of the capacity region

Characterize $\mathcal{L}(\varepsilon; R_1^*, R_2^*)$

- This is joint work with



Jon Scarlett

- We want to characterize $\mathcal{L}(\varepsilon; R_1^*, R_2^*)$ for all points (R_1^*, R_2^*) on the boundary of the capacity region
- For all (R_1^*, R_2^*) in the **interior** of the capacity region

$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \mathbb{R}^2$$

- For all (R_1^*, R_2^*) in the **exterior** of the capacity region

$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \emptyset$$

implying the **strong converse**

■ Mutual informations

$$\mathbf{I}(\rho) := \begin{bmatrix} I_1(\rho) \\ I_{12}(\rho) \end{bmatrix} = \begin{bmatrix} C((1 - \rho^2)S_1) \\ C(S_1 + S_2 + 2\rho\sqrt{S_1S_2}) \end{bmatrix}$$

■ Mutual informations

$$\mathbf{I}(\rho) := \begin{bmatrix} I_1(\rho) \\ I_{12}(\rho) \end{bmatrix} = \begin{bmatrix} C((1 - \rho^2)S_1) \\ C(S_1 + S_2 + 2\rho\sqrt{S_1S_2}) \end{bmatrix}$$

■ Derivative of mutual informations

$$\mathbf{D}(\rho) := \frac{\partial}{\partial \rho} \mathbf{I}(\rho) = \begin{bmatrix} \frac{-S_1\rho}{1+S_1(1-\rho^2)} \\ \frac{\sqrt{S_1S_2}}{1+S_1+S_2+2\rho\sqrt{S_1S_2}} \end{bmatrix}$$

Some Basic Definitions

■ Mutual informations

$$\mathbf{I}(\rho) := \begin{bmatrix} I_1(\rho) \\ I_{12}(\rho) \end{bmatrix} = \begin{bmatrix} C((1 - \rho^2)S_1) \\ C(S_1 + S_2 + 2\rho\sqrt{S_1S_2}) \end{bmatrix}$$

■ Derivative of mutual informations

$$\mathbf{D}(\rho) := \frac{\partial}{\partial \rho} \mathbf{I}(\rho) = \begin{bmatrix} \frac{-S_1\rho}{1+S_1(1-\rho^2)} \\ \frac{\sqrt{S_1S_2}}{1+S_1+S_2+2\rho\sqrt{S_1S_2}} \end{bmatrix}$$

■ Dispersions $V(x, y) := \frac{x(y+2)}{2(x+1)(y+1)}$ and $V(x) := V(x, x)$

$$\mathbf{V}(\rho) := \begin{bmatrix} V_1(\rho) & V_{1,12}(\rho) \\ V_{1,12}(\rho) & V_{12,12}(\rho) \end{bmatrix}$$

where

$$V_1(\rho) := V((1 - \rho^2)S_1), \quad V_{12,12}(\rho) := V(S_1 + S_2 + 2\rho\sqrt{S_1S_2})$$
$$V_{1,12}(\rho) := V((1 - \rho^2)S_1, S_1 + S_2 + 2\rho\sqrt{S_1S_2})$$

Generalization of Inverse CDF of a Gaussian

- For a positive semi-definite matrix \mathbf{V} ,

$$\Psi(z_1, z_2, \mathbf{V}) = \int_{-\infty}^{z_1} \int_{-\infty}^{z_2} \mathcal{N}(\mathbf{0}, \mathbf{V}) \, d\mathbf{u}$$

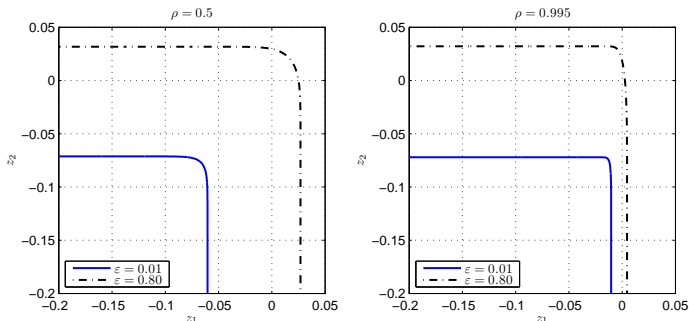
Generalization of Inverse CDF of a Gaussian

- For a positive semi-definite matrix \mathbf{V} ,

$$\Psi(z_1, z_2, \mathbf{V}) = \int_{-\infty}^{z_1} \int_{-\infty}^{z_2} \mathcal{N}(\mathbf{0}, \mathbf{V}) \, d\mathbf{u}$$

- Given $\varepsilon \in (0, 1)$,

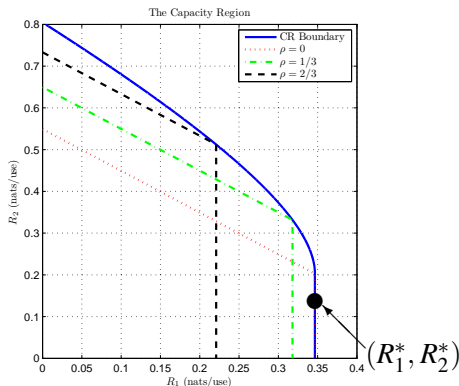
$$\Psi^{-1}(\mathbf{V}, \varepsilon) = \{(z_1, z_2) : \Psi(-z_1, -z_2, \mathbf{V}) \geq 1 - \varepsilon\}.$$



The Main Result: Vertical Boundary

Points on vertical boundary reduce to **scalar dispersion** as sum rate constraint is in **error exponents** regime

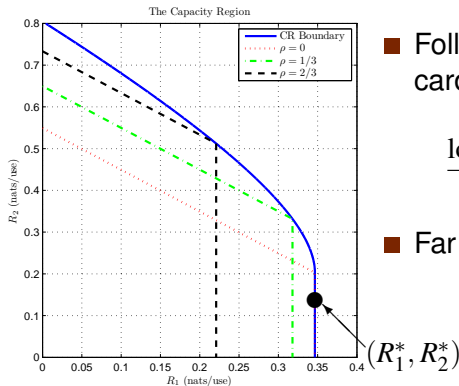
$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \{(L_1, L_2) : L_1 \leq \sqrt{V_1(0)}\Phi^{-1}(\varepsilon)\}$$



The Main Result: Vertical Boundary

Points on vertical boundary reduce to **scalar dispersion** as sum rate constraint is in **error exponents** regime

$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \{(L_1, L_2) : L_1 \leq \sqrt{V_1(0)}\Phi^{-1}(\varepsilon)\}$$



- Following expansion holds for cardinality of first codebook

$$\frac{\log M_{1n}}{n} \approx I_1(0) + \sqrt{\frac{V_1(0)}{n}}\Phi^{-1}(\varepsilon)$$

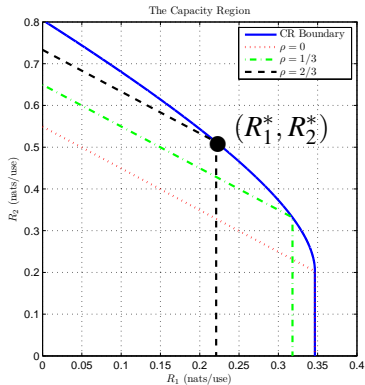
- Far from sum rate constraint

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log(M_{1n}M_{2n}) < I_{12}(0)$$

The Main Result: Curved Boundary

Different behavior in the curved region

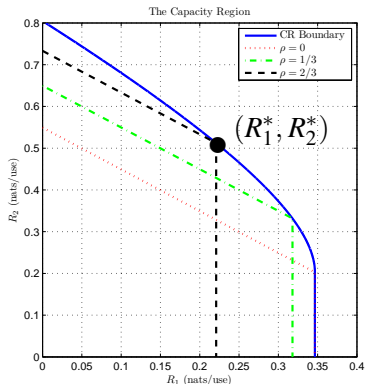
$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \left\{ (L_1, L_2) : \begin{bmatrix} L_1 \\ L_1 + L_2 \end{bmatrix} \in \bigcup_{\beta \in \mathbb{R}} \beta \mathbf{D}(\rho) + \Psi^{-1}(\mathbf{V}(\rho), \varepsilon) \right\}$$



The Main Result: Curved Boundary

Different behavior in the curved region

$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \left\{ (L_1, L_2) : \begin{bmatrix} L_1 \\ L_1 + L_2 \end{bmatrix} \in \bigcup_{\beta \in \mathbb{R}} \beta \mathbf{D}(\rho) + \Psi^{-1}(\mathbf{V}(\rho), \varepsilon) \right\}$$

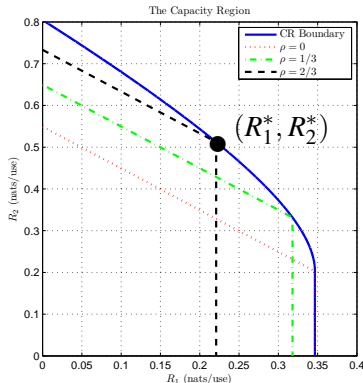


■ $\mathbf{D}(\rho)$ doesn't appear usually

The Main Result: Curved Boundary

Different behavior in the curved region

$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \left\{ (L_1, L_2) : \begin{bmatrix} L_1 \\ L_1 + L_2 \end{bmatrix} \in \bigcup_{\beta \in \mathbb{R}} \beta \mathbf{D}(\rho) + \Psi^{-1}(\mathbf{V}(\rho), \varepsilon) \right\}$$



- $\mathbf{D}(\rho)$ doesn't appear usually
- $\Psi^{-1}(\mathbf{V}(\rho), \varepsilon)$: corresponds using Gaussian with covariance matrix

$$\Sigma(\rho) = \begin{bmatrix} S_1 & \rho\sqrt{S_1 S_2} \\ \rho\sqrt{S_1 S_2} & S_2 \end{bmatrix}$$

Achieving all Second-Order Rate Pairs

$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \left\{ (L_1, L_2) : \begin{bmatrix} L_1 \\ L_1 + L_2 \end{bmatrix} \in \bigcup_{\beta \in \mathbb{R}} \beta \mathbf{D}(\rho) + \Psi^{-1}(\mathbf{V}(\rho), \varepsilon) \right\}$$

Achieving all Second-Order Rate Pairs

$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \left\{ (L_1, L_2) : \begin{bmatrix} L_1 \\ L_1 + L_2 \end{bmatrix} \in \bigcup_{\beta \in \mathbb{R}} \beta \mathbf{D}(\rho) + \Psi^{-1}(\mathbf{V}(\rho), \varepsilon) \right\}$$

- **Non-empty regions in CR** not in trapezium achievable by

$$\mathcal{N} \left(\mathbf{0}, \begin{bmatrix} S_1 & \rho\sqrt{S_1 S_2} \\ \rho\sqrt{S_1 S_2} & S_2 \end{bmatrix} \right)$$

Achieving all Second-Order Rate Pairs

$$\mathcal{L}(\varepsilon; R_1^*, R_2^*) = \left\{ (L_1, L_2) : \begin{bmatrix} L_1 \\ L_1 + L_2 \end{bmatrix} \in \bigcup_{\beta \in \mathbb{R}} \beta \mathbf{D}(\rho) + \Psi^{-1}(\mathbf{V}(\rho), \varepsilon) \right\}$$

- **Non-empty regions in CR** not in trapezium achievable by

$$\mathcal{N} \left(\mathbf{0}, \begin{bmatrix} S_1 & \rho \sqrt{S_1 S_2} \\ \rho \sqrt{S_1 S_2} & S_2 \end{bmatrix} \right)$$

- Use the above distribution dependent on blocklength:

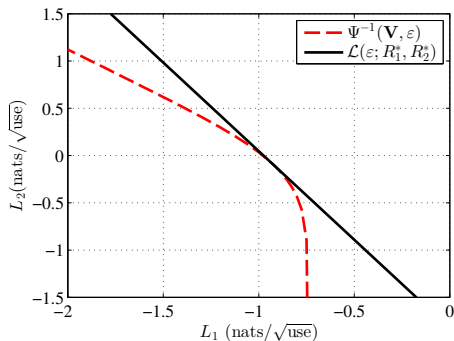
$$\rho_n = \rho + \frac{\beta}{\sqrt{n}}$$

- By a Taylor expansion,

$$\mathbf{I}(\rho_n) \approx \mathbf{I}(\rho) + (\rho_n - \rho) \mathbf{D}(\rho) = \mathbf{I}(\rho) + \frac{\beta \mathbf{D}(\rho)}{\sqrt{n}}$$

explaining the **slope term**.

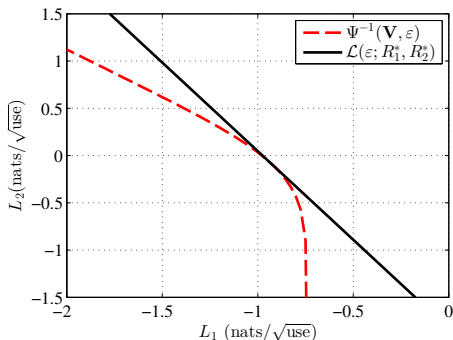
Illustration of Second-Order Coding Rates



$$S_1 = S_2 = 1 \text{ and } \rho = \frac{1}{2}$$

$\mathcal{L}(\varepsilon; R_1^*, R_2^*)$ is a
half-space

Illustration of Second-Order Coding Rates

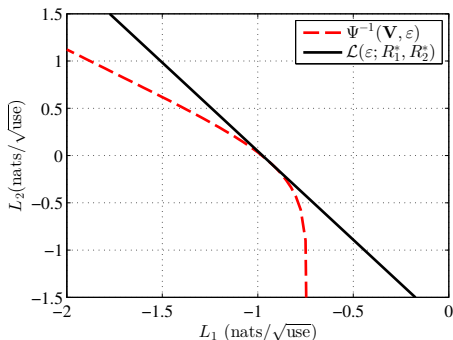


$$S_1 = S_2 = 1 \text{ and } \rho = \frac{1}{2}$$

$\mathcal{L}(\varepsilon; R_1^*, R_2^*)$ is a
half-space

- Second-order rates achieved using a **single input distribution** $\mathcal{N}(\mathbf{0}, \Sigma(\rho))$ is **not optimal**

Illustration of Second-Order Coding Rates



$$S_1 = S_2 = 1 \text{ and } \rho = \frac{1}{2}$$

$\mathcal{L}(\varepsilon; R_1^*, R_2^*)$ is a
half-space

- Second-order rates achieved using a **single input distribution** $\mathcal{N}(\mathbf{0}, \Sigma(\rho))$ is **not optimal**
- Need to vary input distribution with blocklength to achieve all points in $\mathcal{L}(\varepsilon; R_1^*, R_2^*)$

- 1 Motivation, Background and History
- 2 Gaussian Interference Channel with Very Strong Interference
- 3 Gaussian MAC with Degraded Message Sets
- 4 Conclusion

Conclusion

- **Asymptotic expansions** for NIT problems with non-vanishing error probabilities is a very fertile area of research

Conclusion

- **Asymptotic expansions** for NIT problems with non-vanishing error probabilities is a very fertile area of research
- Other single-user that are solved include:
 - 1 Quasi-static MIMO fading channels (Yang-Durisi-Koch-Polyanskiy)
 - 2 Channels with discrete state (Tomamichel-Tan)
 - 3 Dirty-paper coding (Scarlett)

Conclusion

- **Asymptotic expansions** for NIT problems with non-vanishing error probabilities is a very fertile area of research
- Other single-user that are solved include:
 - 1 Quasi-static MIMO fading channels (Yang-Durisi-Koch-Polyanskiy)
 - 2 Channels with discrete state (Tomamichel-Tan)
 - 3 Dirty-paper coding (Scarlett)
- **Shameless self-promotion:**

V. Y. F. Tan

Asymptotic expansions in IT with non-vanishing error probabilities

Now Publishers

Foundations and Trends in Comms and Inf. Th.

