

Rank Minimization over Finite Fields

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Connection between Two Areas of Study

Area of Study	Matrix Completion Rank Minimization	Rank-Metric Codes
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- Assume **linear** code. Rank minimization over finite field:

$$\hat{\mathbf{X}} = \arg \min_{\mathbf{X} \in \text{coset}} \text{rank}(\mathbf{X})$$

When do low-rank errors occur?

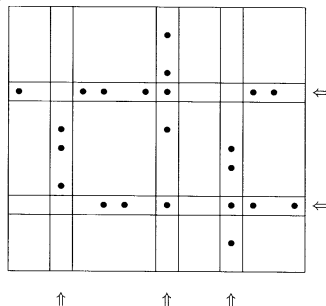
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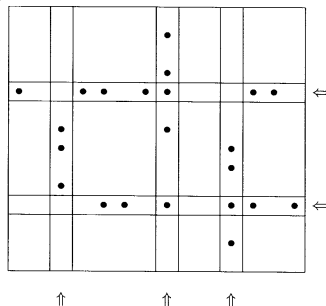


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- Given $(\mathbf{y}^k, \mathbf{H}^k)$, find **necessary** and **sufficient** conditions on k and **sensing model** such that recovery is **reliable**, i.e., $\mathbb{P}(\mathcal{E}_n) \rightarrow 0$

Main Results

- k : Num. of linear measurements
- n : Dim. of matrix \mathbf{X}
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Achievability (Uniform)	$k > (2 + \varepsilon)\gamma(1 - \gamma/2)n^2$	$\mathbb{P}(\mathcal{E}_n) \rightarrow 0$ $\mathbb{P}(\mathcal{E}_n) \approx q^{-n^2 E(R)}$

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Achievability (Sparse)	$k > (2 + \varepsilon)\gamma(1 - \gamma/2)n^2$	$\mathbb{P}(\mathcal{E}_n) \rightarrow 0$
Achievability (Noisy)	$k \gtrsim (3 + \varepsilon)(\gamma + \sigma)n^2$ (q assumed large)	$\mathbb{P}(\mathcal{E}_n) \rightarrow 0$

A necessary condition on number of measurements

Given k measurements $y_a \in \mathbb{F}_q$ and sensing matrices $\mathbf{H}_a \in \mathbb{F}_q^{n \times n}$, we want a necessary condition for reliable recovery of \mathbf{X} .

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Proposition (Converse)

Assume

- \mathbf{X} drawn *uniformly at random* from all matrices in $\mathbb{F}_q^{n \times n}$ of rank $\leq r$
- Sensing matrices $\mathbf{H}_a, a = 1, \dots, k$ *jointly independent* of \mathbf{X}
- $r/n \rightarrow \gamma$ (constant)

If the number of measurements satisfies

$$k < (2 - \varepsilon)\gamma \left(1 - \frac{\gamma}{2}\right) n^2$$

then $\mathbb{P}(\hat{\mathbf{X}} \neq \mathbf{X}) \geq \varepsilon/2$ for all n sufficiently large.

A sensing model: Uniform model

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- Each entry of each sensing matrix \mathbf{H}_a is i.i.d. and has a **uniform** distribution in \mathbb{F}_q :

$$\mathbb{P}([\mathbf{H}_a]_{i,j} = h) = \frac{1}{q}, \quad \forall h \in \mathbb{F}_q$$

The min-rank decoder

- We employ the **min-rank decoder**

$$\begin{array}{ll} \text{minimize} & \text{rank}(\tilde{\mathbf{X}}) \\ \text{subject to} & \langle \mathbf{H}_a, \tilde{\mathbf{X}} \rangle = y_a, \quad a = 1, \dots, k \end{array}$$

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$$\mathcal{E}_n := \{|\mathcal{S}| > 1\} \cup (\{|\mathcal{S}| = 1\} \cap \{\mathbf{X}^* \neq \mathbf{X}\})$$

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- We want the solution to be **unique** and **correct**

Proposition (Achievability under uniform model)

Assume

- Sensing matrices \mathbf{H}_a drawn *uniformly*
- Min-rank decoder is used
- $r/n \rightarrow \gamma$ (constant)

If the number of measurements satisfies

$$k > (2 + \varepsilon)\gamma \left(1 - \frac{\gamma}{2}\right) n^2$$

then $\mathbb{P}(\mathcal{E}_n) \rightarrow 0$.

Proof Sketch

$$\mathcal{E}_n = \bigcup_{\mathbf{Z} \neq \mathbf{X}: \text{rank}(\mathbf{Z}) \leq \text{rank}(\mathbf{X})} \{\langle \mathbf{Z}, \mathbf{H}_a \rangle = \langle \mathbf{X}, \mathbf{H}_a \rangle, \forall a = 1, \dots, k\}$$

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By the union bound, the error probability can be bounded as

$$\mathbb{P}(\mathcal{E}_n) \leq \sum_{\mathbf{Z} \neq \mathbf{X}: \text{rank}(\mathbf{Z}) \leq \text{rank}(\mathbf{X})} \mathbb{P}(\langle \mathbf{Z}, \mathbf{H}_a \rangle = \langle \mathbf{X}, \mathbf{H}_a \rangle, \forall a = 1, \dots, k)$$

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Remark: Can be extended to noisy case

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The *rate* of a sequence of linear measurement models is defined as

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Definition

The *reliability function* of the min-rank decoder is defined as

$$E(R) := \lim_{n \rightarrow \infty} -\frac{1}{n^2} \log_q \mathbb{P}(\mathcal{E}_n)$$

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Proposition (Reliability Function of Min-Rank Decoder)

Assume

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- Min-rank decoder is used
- $r/n \rightarrow \gamma$ (*constant*)

Then,

$$E(R) = \left| (1 - R) - 2\gamma \left(1 - \frac{\gamma}{2}\right) \right|^+$$

Note $|x|^+ := \max\{x, 0\}$.

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- **de Caen's** lower bound: Let $\mathcal{B}_1, \dots, \mathcal{B}_M$ be events:

$$\mathbb{P} \left(\bigcup_{m=1}^M \mathcal{B}_m \right) \geq \sum_{m=1}^M \frac{\mathbb{P}(\mathcal{B}_m)^2}{\sum_{m'=1}^M \mathbb{P}(\mathcal{B}_m \cap \mathcal{B}_{m'})}.$$

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- Exploit pairwise independence to make statements about **error exponents** (linear codes achieve capacity in symmetric DMCs)

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Sparse sensing model

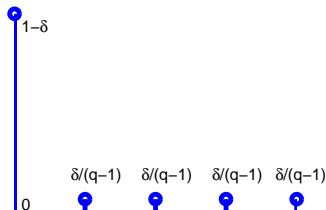
- Assume as usual that \mathbf{X} is non-random
- $\text{rank}(\mathbf{X}) \leq r = \gamma n$
- Sensing matrices are sparse

$$\begin{aligned} \langle \mathbf{H}_1, [\mathbf{X}] \rangle &= \mathbf{y}_1 \\ &\vdots \\ \langle \mathbf{H}_k, [\mathbf{X}] \rangle &= \mathbf{y}_k \end{aligned}$$

- Arithmetic still performed in \mathbb{F}_q

Sparse sensing model

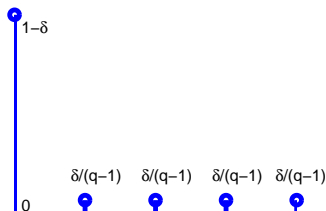
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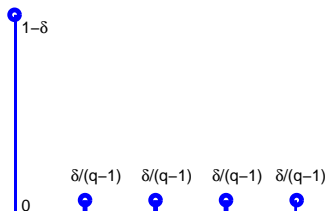


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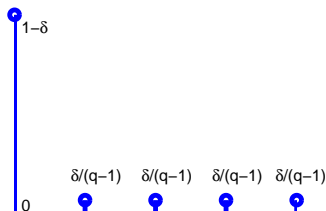


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- How fast can δ , the sparsity factor, decay with n for reliable recovery?

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- Sensing matrices \mathbf{H}_a drawn according to δ -sparse distribution
- Min-rank decoder is used
- $r/n \rightarrow \gamma$ (constant)

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and the number of measurements satisfies

$$k > (2 + \varepsilon)\gamma \left(1 - \frac{\gamma}{2}\right) n^2$$

then $\mathbb{P}(\mathcal{E}_n) \rightarrow 0$.

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<http://arxiv.org/abs/1104.4302>