

# Structure Learning of Sparse Random Ising Models

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## 1 Graphical Models

# Outline

- 1 Graphical Models
- 2 Problem Definition

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- 3 Necessary Conditions on Sample Complexity

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- ➌ Necessary Conditions on Sample Complexity
- ➍ Sufficient Conditions on Sample Complexity
  - Correlation Thresholding
  - Conditional Mutual Information Thresholding

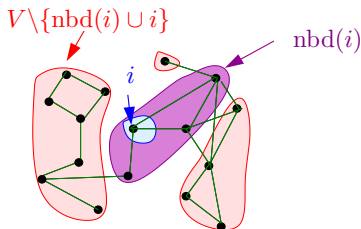
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  - Correlation Thresholding
  - Conditional Mutual Information Thresholding
- ⑤ Conclusion

# Graphical Models: Introduction

- Graph  $G = (V, E)$  represents a multivariate prob. distribution of a random vector  $\mathbf{X} = (X_1, \dots, X_d)$  indexed by  $V = \{1, \dots, d\}$
- Node  $i \in V$  corresponds to random variable  $X_i$
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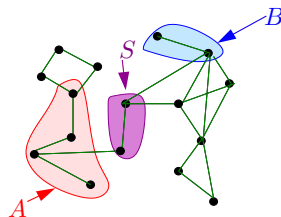
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$$X_i \perp\!\!\!\perp \mathbf{X}_{V \setminus \{nbd(i) \cup i\}} \mid \mathbf{X}_{nbd(i)}$$

Local Markov Property



$$\mathbf{X}_A \perp\!\!\!\perp \mathbf{X}_B \mid \mathbf{X}_S$$

Global Markov Property



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- Desideratum 2: Low computational complexity
- Motivation: High-dimensional data (microarray, social networks)

# Related Work on Learning Graphical Models

## Efficient Algorithms for Structure Learning

- ML for **trees**: Max-weight spanning tree (Chow & Liu 68)
  - Error exponents (T., Anandkumar, Tong, Willsky IT-'11)
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- **Conditional independence** tests for bounded degree graphs (Abbeel et al. '06, Bresler et al. '09)
- **Convex optimization**:  $\ell_1$  regularization (Dudik et al. '04, Lee et al. '06, Meinshausen & Buehlmann '06, Ravikumar et al. '10)
- **Information-theoretic** lower bounds (Santhanam & Wainwright '08)

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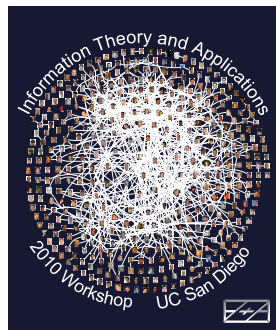
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- We consider the case where the **underlying graph**  $G$  is **random**
- Relax the assumption that graph comes from a particular set
- “Real-world” networks can be modeled by random graphs
- Our work is a first-step in understanding the fundamental limits in learning **random graphical models**

- **Ising** model
- Markov on **Erdős-Rényi** ensemble  $G_n \sim \mathcal{G}(n, \frac{c}{n})$



# Crisis = Danger + Opportunity

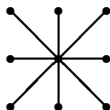
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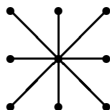




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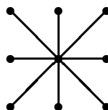


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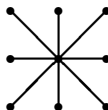
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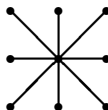
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- **Correlation decay**: Influences of “faraway” nodes on node  $i$  are negligible, model behaves locally as a tree distribution
- **Tree-based** algorithms (Chow-Liu, Thresholding) may work

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$$P(\mathbf{x}|G) \propto \exp \left( \sum_{(i,j) \in E} J_{i,j} x_i x_j \right), \quad \mathbf{x} \in \{\pm 1\}^n$$

Assumptions:

- **Ferromagnetism**:  $J_{i,j} \in [J_{\min}, J_{\max}] \subset (0, \infty)$  for all  $(i,j) \in E$



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## Theorem (Converse)

*There exists an  $\varepsilon > 0$  such that if*

$$k \leq \varepsilon c \log n,$$

*then,*

$$\lim_{k, n \rightarrow \infty} \Pr \left( \hat{G}_n(\mathbf{x}^k) \neq G_n \right) = 1$$

*for any estimator  $\hat{G}_n(\cdot)$ .*

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Moral of the story: Need  $k = \Omega(c \log n)$  samples for consistent recovery

- Follows closely the converse technique in Bresler et al. '09.
- Main modification: Underlying graph not deterministic so counting argument needs to be modified
- Focus on graphs “with the **highest likelihoods**”
- Note from

$$k \leq \varepsilon c \log n,$$

that number of samples  $k$  is required to grow **linearly** with the **average degree**  $c$

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- Set  $(u, v) \in \hat{G}_n$  iff

$$\hat{C}_{u,v}^k \geq \delta(J_{\min}, J_{\max})$$

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## Theorem (Structural Consistency of CorrThres)

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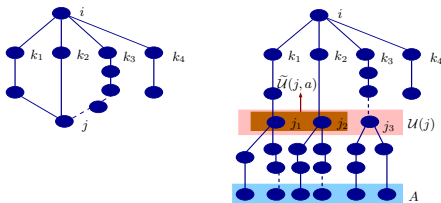
$$\lim_{\substack{k, n \rightarrow \infty \\ k = \Omega(\log n)}} \Pr \left( \text{CorrThres}(\{\hat{C}_{u,v}^k\}_{(u,v) \in V^2}; \delta); \neq G_n \right) = 0$$

# Correlation Thresholding: Why / How does it work?

- Correlations are higher on edges than non-edges for **nearly homogeneous Ising models** on  $\mathcal{G}(n, \frac{c}{n})$

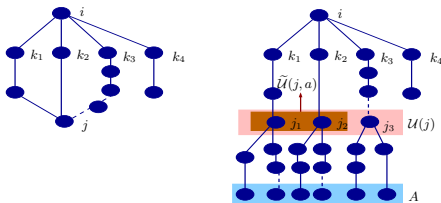
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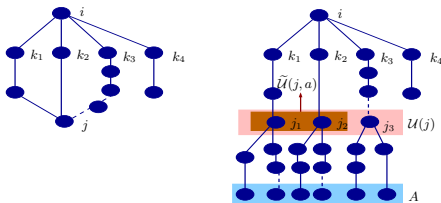


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- Prove result for **exact statistics**; generalization to sample statistics using large deviations
- Can **homogeneity** assumption be removed?

# Separation Property

- Fact: For sets  $A, B, S \in V$ , if  $S$  separates  $A, B$ , then

$$I(X_A; X_B | X_S) = 0$$

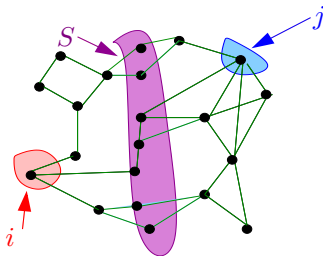
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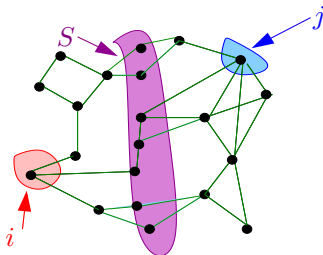
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- $\tau_{k,n}$  is the threshold
- Depends on number of variables  $n$  and sample size  $k$

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## Theorem (Structural Consistency of CMIT)

*For a.e. graph  $G_n$ , we have*

$$\lim_{\substack{k, n \rightarrow \infty \\ k = \omega(\log n)}} \Pr(\text{CMIT}(\mathbf{x}^k; \tau_{k,n}); \neq G_n) = 0$$

# Conditional MI Thresholding: Why / How does it work?

- Challenge: Separators in graphical models may be large, i.e.,

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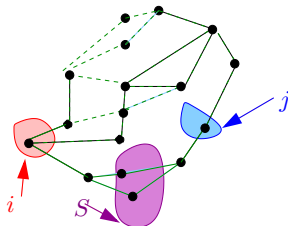
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- Approximate** separation?
- In such random graphical models, the size of an approximate separator is  $\leq 2$  asymptotically



- Ignore effects of long paths separating  $i$  and  $j$

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- <http://arxiv.org/abs/1011.0129>